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SEAT No.:			
[Total	Nο	of Pages	• 2

M.E. (Electrical Control Systems) ADVANCED DRIVES AND CONTROL

(2017 Course) (Semester - III) (603101)

Time: 3	Hours] [Max. Marks :50
Instructi	ons to the candidates:
1)	Neat diagrams must be drawn whenever necessary.
2)	Figures to the right indicate full marks.
3)	Assume suitable data if necessary.
4)	Use of logarithmic tables, eletronic pocket calculator and steam tables is allowed.
<i>Q1)</i> a)	Compare A.C. and D. C. Drives from following point of view: [5]
	i) Available supply and nature of output voltage and controller.
	ii) Electric drive of the motor and controller action.
b)	Write notes on Dynamics d - q model in connection with speed control of Induction motor. [4]
c)	Draw a neat circuit diagram of the system model and derive the transfer function of converter fed D.C. drives.gun [4]
d)	Write notes on sensor less vector control of three phase induction motor.[5] OR
Q2) a)	With the help of neat block diagram of field controlled D.C. motor, derive the transfer function of the variable speed drive. How is the field weakening achieved? [5]
b)	Explain Static Krammer control of drive using Induction motor. [5]
c)	Explain, in connection with speed control of Induction motor, the following terms: [4]
	i) Direct vector control
	ii) Indirect vector control
d)	Explain variable frequency control of three phase induction motor. [4]

Q3)	a)	Explain in detail with reference to synchronous motor drive: [8]
		i) Trapezoidal SPM drive
		ii) Sinusoidal SPM drive
	b)	Discuss synchronous reluctance concept of Synchronous motor drive. [8]
		OR
Q4)	a)	Obtain Dynamic d - q model of Synchronous motor drive. [8]
	b)	Write notes on Wound field machine drives and switched reluctance motor drives. [8]
Q5)	a)	Write a note on industrial application of PID controller. [8]
	b)	Explain the application of phase locked loop (PLL) in the closed loop control of electric drive. [8]
		OR
Q6)	a)	In the closed loop control of electric drive, explain the effect of RMS voltage variation on the performance. [8]
	b)	Explain the role of Proportional and Integral controller in the closed loop control of electric drive. [8]
		control of electric drive.