



**K. K. Wagh Institute of Engineering Education & Research, Nashik**  
(An Autonomous Institute From A.Y. 2022-23)

WINTER-2025	
Exam Seat No.:	
Academic Year:2025-2026	Semester:IV
Class:SY	Program:B.Tech
Branch Code:ROB	Pattern:2023
Name of Course:Computer Graphics for Robotics	Course Code:2312212
Max. Marks:60	Duration:2.30 Hrs.

**Instructions:** Candidates should read carefully the instructions printed on the Question Paper and on the cover page of the Answer Book, which is provided for their use.

1. This question paper contains 02page(s).
2. Answer to each new question is to be started on a new page.
3. Assume suitable data wherever required, but justify it.
4. Draw the neat labelled diagrams, wherever necessary.
5. The last columns indicates the Course Outcome and level of Blooms Taxonomy of the Question/sub-question.

**Marks CO**

**Question No. 1**

- 1a) Determine the point of intersection of the line AB and CD having co-ordinates A(1, 3, 0.143) B(2, 5, 7), C(-3, 4, 1), D(1, 2, -3) or show that the lines do not intersect. (6) CO1

**Question No. 2**

- 2a) Perform  $50^\circ$  rotation of a triangle A (1, 5), B (6, 3), C (5, 8) about the point C. (6) CO2

**Question No. 3**

- 3a) For the data given below, use Lagrange Interpolation method to estimate Y for X = 2 . (8) CO2  
X=[1 3 4 ]; Y = [10 14 21 ]

**OR**

- 3b) What is Lagrange interpolation method? Write formulae for first order and second order interpolation. Also state the properties and applications of Lagrange interpolation method. (8) CO2

- 3c) For the following data, use inverse distance weighting method to interpolate at  $x = 8, y = 15$ . (8) CO2

x	5	12	15	23
y	10	7	13	28
z	69	25	98	47

**OR**

- 3d) Explain the application of quaternions to obtain the combined roll, pitch and yaw motion of a robot gripper. (8) CO2

**Question No. 4**

- 4a) What is sweep surface? Formulate a mathematical formulation to generate it. Explain with suitable example. (8) CO3

**OR**

- 4b) A line with end point (1, 5, 0) and (4, 7, 0) is simultaneously revolved about x-axis by  $360^\circ$  and translated along x-axis by 10 units to generate sweep surface. Obtain the point on this sweep surface for  $t = 0.2$  and  $s = 0.3$ . Where  $t$  is parameter for line and  $s$  is parameter for revolution and translation. (8) CO3
- 4c) Obtain x co-ordinate of a point on the Bezier surface patch at  $u=0.4$  and  $v= 0.6$  using following control points: (8) CO3

$$\begin{bmatrix} (2, 5, 12) & (5, 5, 6) & (8, 5, 6) \\ (2, 8, 5) & (5, 8, 12) & (8, 8, 5) \\ (2, 3, 6) & (5, 3, 5) & (8, 3, 12) \end{bmatrix}$$

**OR**

- 4d) For the control points (1, 3), (2, 4), (3, 1), (4, 2), (5, 4). Determine the  $x$  and  $y$  co-ordinates of a point on cubic B-spline curve for its second segment at parameter value  $t = 0.4$ . (8) CO3

**Question No. 5**

- 5a) Explain following terms related to Geometric algebra (8) CO4
- i) Multi vector
  - ii) Outer product
  - iii) Inner product
  - iv) Geometric product

**OR**

- 5b) Derive an expression to show the basis blades of a bi-vector in 3D space. (8) CO4
- 5c) Obtain the outer and inner product of vectors  $u = [4 \ 6 \ 5 \ 2]^T$  and  $v = [5 \ 10 \ 8 \ 4]^T$  (8) CO4

**OR**

- 5d) Explain the applications of Geometric algebra in robotics (8) CO4

**..... End of question paper.....**