





- 3c) **Build** mathematical model for Translational mechanical system using basic building blocks and determine transfer function of the system. (8) CO2

**OR**

- 3d) **Build** mathematical model for Thermal system using basic building blocks. (8) CO2

**Question No. 4**

- 4a) **Outline** the sketch to depict unit step response of 2nd Order system. for various damping ratio  $\zeta = 0, 1, >1, <1$ . (8) CO3

**OR**

- 4b) **Differentiate** between relative and absolute stability criteria also Determine the type of damping for the given system. (8) CO3

$$\frac{C(s)}{R(s)} = \frac{2}{s^2 + 2s + 1}$$

- 4c) **Analyze** the given transfer function of the system for relative stability criteria by pole zero plot. (8) CO3

$$T.F. = \frac{K(s+6)}{s(s+2)(s+5)(s^2+7s+12)}$$

**OR**

- 4d) **Analyze** the given transfer function of the system for absolute stability by Routh's criteria. (8) CO3

$$2s^3 + 4s^2 + 4s + 12 = 0$$

**Question No. 5**

- 5a) **Summarize** the different types of timers and counters used in PLC programming. (8) CO4

**OR**

- 5b) **Deduce** ladder program for following logic gates with truth table AND, OR, EX-OR, EX-NOR. (8) CO4

- 5c) **Justify** with neat sketch the use of a PID controller with a suitable example. (8) CO4

**OR**

- 5d) **Compare** Integral and Derivative controller with reference to 1. Transfer function 2. Characteristic plot 3. Advantage 4. Limitation. (8) CO4

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