SEAT No. : [Total No. of Pages: 2

APR-17/TE/Insem.-43

DIGITAL SIGNAL PROCESSING APPLICATIONS T.E. (Computer Engineering)

(2012 Pattern) (Semester - II) (310253)

Instructions to the candidates: Time: I Hour

[Max. Marks: 30

- Attempt Q1 or Q2, Q3 or Q4, Q5 or Q6.
- Neat diagrams must be drawn wherever necessary.
- Assume suitable data if necessary.
- QI) a) State the mathematical models used to represent a DT system. Define these models with mathematical form.
- 5 Define the Impulse Response of a DT system and show that for a causal

h(n) = 0 for n < 0

U

- Q2) a) A CT signal having frequency 50 Hz is sampled at a rate of 1200 samples/ sec. Obtain -
- Number of samples per cycle
- E Digital/Discrete frequency f and ω
- E Minimum sampling rate to avoid aliasing effect
- Period of a DT signal

U

- 6 State the Linearity, causality and stability properties of a DT system. [5]
- Q3) a) State and prove the time reversal property of Fourier Transform (FT).[5]
- 0 computational complexity of N point DFT. the basic butterfly structure for DIF FFT algorithm and hence obtain the What do you understand by 'Indexing in Bit-Reversal' in FFT? Draw

MAR 2017

- Q4) a) Perform following circular shifting operations on a given DT signal $x(n)=\{4,2,-1,3\}$ with N=4 and N=5.
- $x((n-2))_{N}$

 $x((n+1))_{\lambda}$

un

- 6) means of twiddle factor W and compute twiddle factors for N = 4. [5] What is the significance of 'N' in N point DFT? Define N point DFT by
- Q5) a) Define ROC of ZT. How many possible ROCs a single ZT may have? Give one example. T
- 5 Obtain ZT of a DT signal using ZT properties where

x(n) = n.u(n-1) Specify the ROC

Ui

Q6) a) Draw a Pole Zero plot for a system described as-

y(n) = x(n) - x(n-1) + 0.2y(n-1) + 0.15y(n-2)

Un

9 Define the term system function H(Z). Express it in the form of pole zero system and define it for FIR and IIR system. Ui

222